

ECEN430

Advanced Mechatronics II

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@misc{Hector SLAM's image registration,
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@book{Introduction to Autonomous Mobile Robots | The MIT Press,
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@book{Wiley: Control Systems Engineering, 6th Edition - Norman S. Nise,
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@book{Artificial Intelligence - Rob Callan - Palgrave Higher Education,
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@misc{Hector SLAM for robust mapping in USAR environments,
url={ http://tedusar.eu/cms/sites/tedusar.eu.cms/files/Hector_SLAM_USAR_Kohlbrecher_RRSS_Graz_2012.pdf} }

@misc{Hector SLAM indepth paper,
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@misc{Nonlinear Least-Squares Problems with the Gauss-Newton and Levenberg-Marquardt Methods,

url= { <https://www.math.lsu.edu/system/files/MunozGroup1%20-%20Presentation.pdf> } }

@misc{SOLVING NONLINEAR LEAST-SQUARES PROBLEMS WITH THE GAUSS-NEWTON AND LEVENBERG-MARQUARDT METHODS,

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